



International Symposium
Qualification of dynamic analyses of dams and their equipments
and of probabilistic assessment seismic hazard in Europe
31th August – 2nd September 2016 – Saint-Malo

Sadri Mével



IMPROVING GRAVITY DAMS SIMPLIFIED MODELS : WHY WE SHOULD GO ON



Saint-Malo © Yannick LE GAL

SUMMARY

1.WHY DO WE STILL NEED SIMPLIFIED MODELS?

2.A SIMPLIFIED MODEL WHICH WORKS WELL: ASSESSMENT OF THE SEISMIC SLIDING

THE SLIDING PROBLEM

A SIMPLIFIED MODEL

TESTS AND APPLICATIONS

3.IMPROVING SIMPLIFIED MODELS

SOIL-STRUCTURE INTERACTION

VERTICAL FLUID BEHAVIOR AND FLUID-STRUCTURE INTERACTION

4. CONCLUSIONS AND PERSPECTIVES

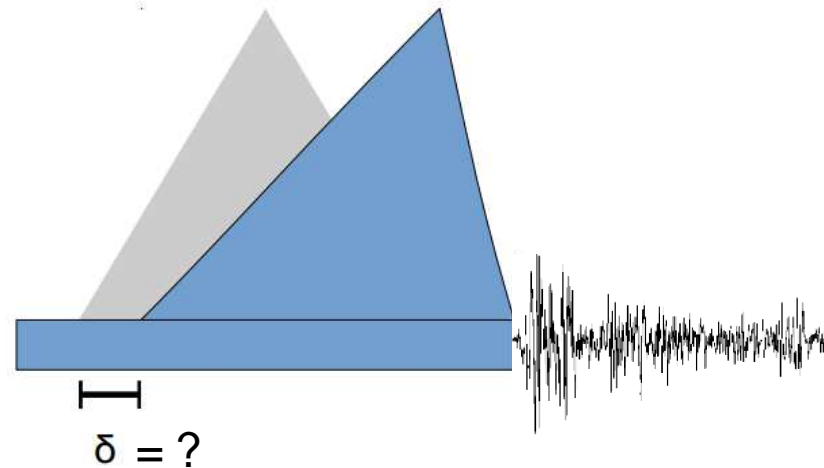
WHY DO WE STILL NEED SIMPLIFIED MODELS?

- Necessary companion for all more complex simulations, as an **error detection tool**
- Allow to investigate the **physics of the problem** – instead of only relying on a “**black box**” that necessarily mixes several aspects
- Well suited to small or medium-size dams for which **data often lack** to set-up complex models
- Allow investigating the **influence of the various parameters**

These reasons explain why we keep doing simplified modeling for the static resistance of gravity dams (whereas they do not entirely capture some important issues like upstream crack propagation)

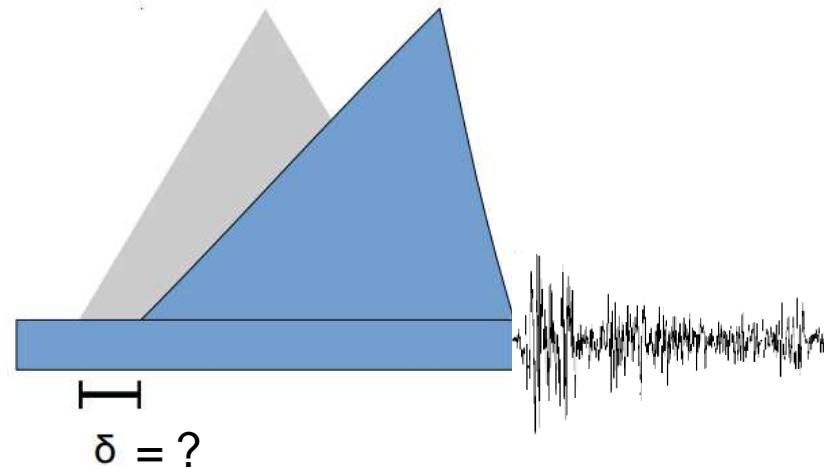
A SIMPLIFIED MODEL WHICH WORKS WELL: ASSESSMENT OF THE SEISMIC SLIDING

THE SLIDING PROBLEM



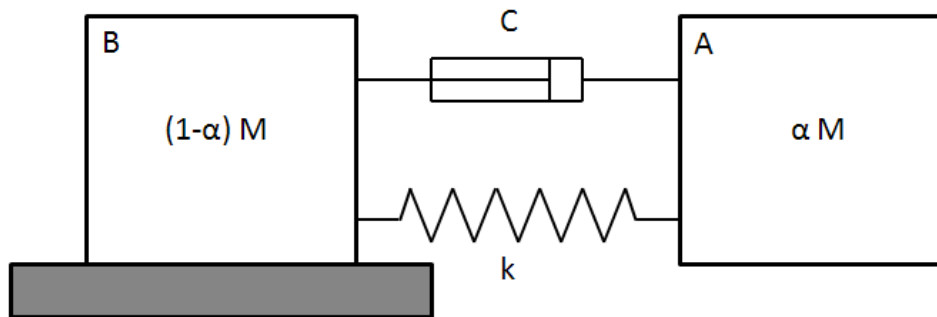
- **If it is impossible to meet the non-sliding criterion during the earthquake**
 - The dam may slide over its foundation
 - Along what distance it is likely to slide? mm? cm? m?
- **Which method could be used to assess this distance?**
 - Finite elements model
 - Newmark's methods
 - **Any other?**

A SIMPLIFIED MODEL FOR SLIDING



- **A geometry**
 - 2D section
- **Some hypothesis**
 - The behavior of the reservoir can be approximated by **added-masses**
 - The shear force at the foundation only depends on the 1st mode
 - The other modes can be considered as **rigid modes**
 - The earthquake acceleration is **horizontal**

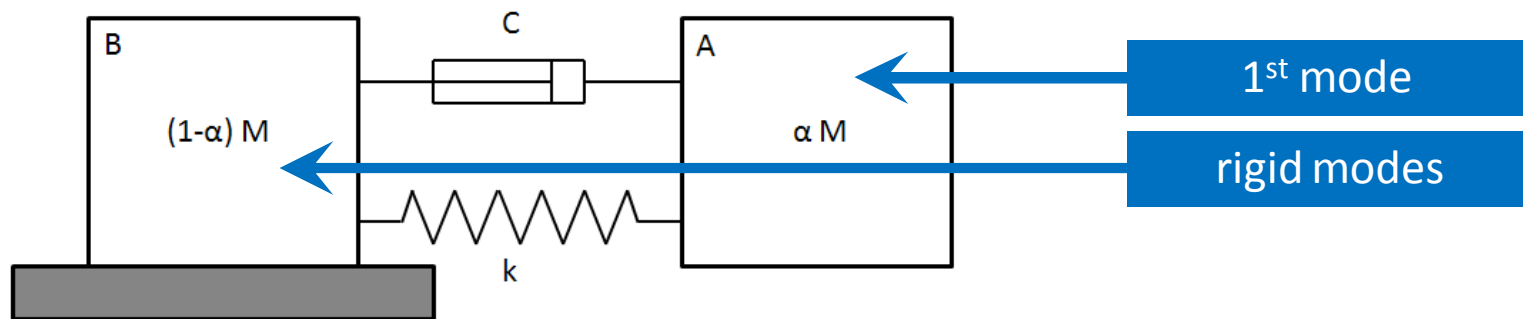
A SIMPLIFIED MODEL FOR SLIDING



$$k = \alpha M \omega^2$$
$$C = 2 \xi \alpha M \omega$$

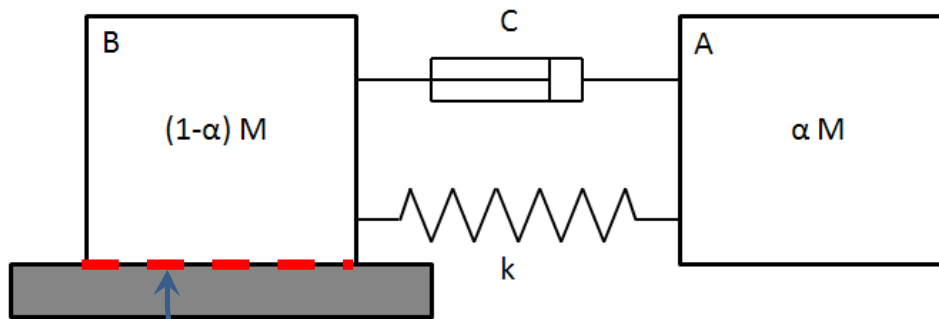
- **With only two degrees of freedom**
 - A : the first mode, oscillating
 - B : the other modes, rigid
- **With only four parameters**
 - α : fraction of modal mass of the first mode ($\alpha = m_1/M$ with M : total mass)
 - ω : pulsation frequency of the first mode
 - ξ : damping ratio of the first mode
 - A contact law ?

A SIMPLIFIED MODEL FOR SLIDING



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A SIMPLIFIED MODEL FOR SLIDING



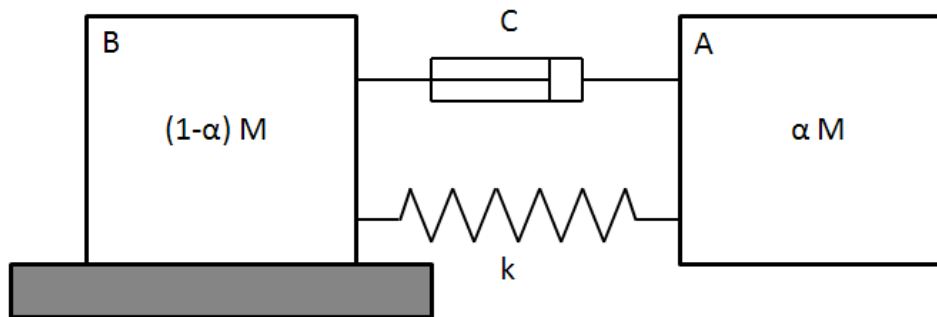
Mohr-Coulomb : $T_{\text{dyna}} < T_{\text{max}} - T_{\text{stat}} = N \tan(\varphi) - T_{\text{stat}}$

- **The limit-acceleration : defined by Newmark (1965)**

- $a_{\text{lim}} = T_{\text{dyna}} / M$
- a_{lim} is the max. « static » acceleration for which the dam does not slide

- For a dam with vertical upstream face :
$$a_{\text{lim}} = \frac{(Mg - SP) \tan \varphi - HS_x}{M + M_{\text{added}}}$$

A SIMPLIFIED MODEL FOR SLIDING

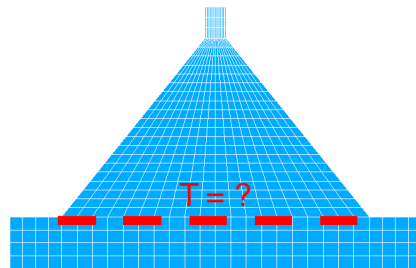


$$k = \alpha M \omega^2$$
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- **Only four parameters**
 - α : fraction of modal mass of the first mode (M : total mass)
 - ω : pulsation frequency of the first mode
 - ξ : damping ratio of the first mode
 - a_{lim} : limit acceleration
- **A model which is able to estimate the shear force at the foundation**

A « PROOF » : THE SHEAR FORCE

- Let's compare the shear force at the foundation, in each model
 - In a finite elements model



$$\begin{aligned}
 T &= \underline{\underline{\Delta}} \cdot (\underline{\underline{K}} \underline{\underline{U}} + \underline{\underline{C}} \underline{\underline{\dot{U}}}) \\
 &= \underline{\underline{\Delta}} \underline{\underline{K}} \left(\underline{\underline{D}}_1 a_1 q_1(t) + \sum_{i=2}^N \underline{\underline{D}}_i a_i q_i(t) \right) \\
 &\quad + \underline{\underline{\Delta}} \underline{\underline{C}} \left(\underline{\underline{D}}_1 a_1 \dot{q}_1(t) + \sum_{i=2}^N \underline{\underline{D}}_i a_i \dot{q}_i(t) \right) \\
 &= \dots \\
 &= (M - m_1) a_s(t) + \omega_1^2 m_1 q_1(t) + 2\xi_1 \omega_1 m_1 \dot{q}_1(t)
 \end{aligned}$$

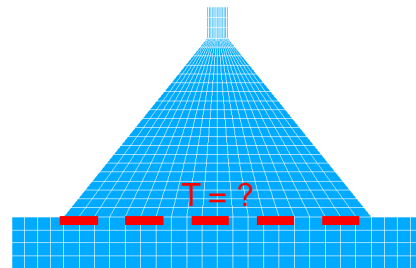
- $\underline{\underline{M}} ; \underline{\underline{K}} ; \underline{\underline{C}}$: mass, stiffness & damping matrices
- $\underline{\underline{D}}_i$: modal base
- $\underline{\underline{\Delta}}$: influence vector
- $\underline{\underline{X}}$: nodes displacements vector
- Modal masses : $m_i = \frac{(\underline{\underline{D}}_i \underline{\underline{M}} \underline{\underline{\Delta}})^2}{\underline{\underline{D}}_i \underline{\underline{M}} \underline{\underline{D}}_i}$
- Participation factors : $a_i = \frac{\underline{\underline{D}}_i \underline{\underline{M}} \underline{\underline{\Delta}}}{\underline{\underline{D}}_i \underline{\underline{M}} \underline{\underline{D}}_i}$

Detailed demonstration is given in ref [1]

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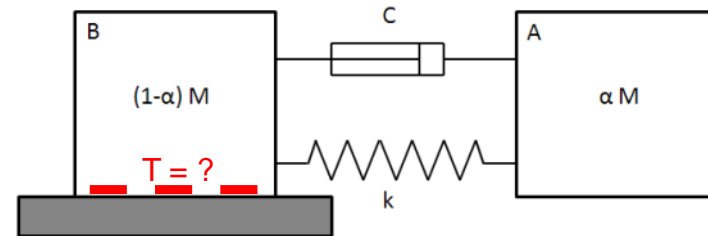
= ...

$$= (M - m_1) a_s(t) + \omega_1^2 m_1 q_1(t) + 2\xi_1 \omega_1 m_1 \dot{q}_1(t)$$

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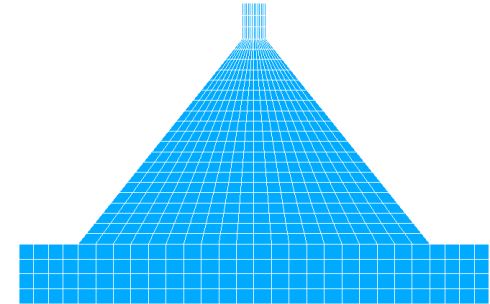
- Same equation for the simplified model !



SHEAR FORCE CALCULATION

- **With an example**

- Shear force calculated with ANSYS[®]
- Shear force calculated with the simplified method



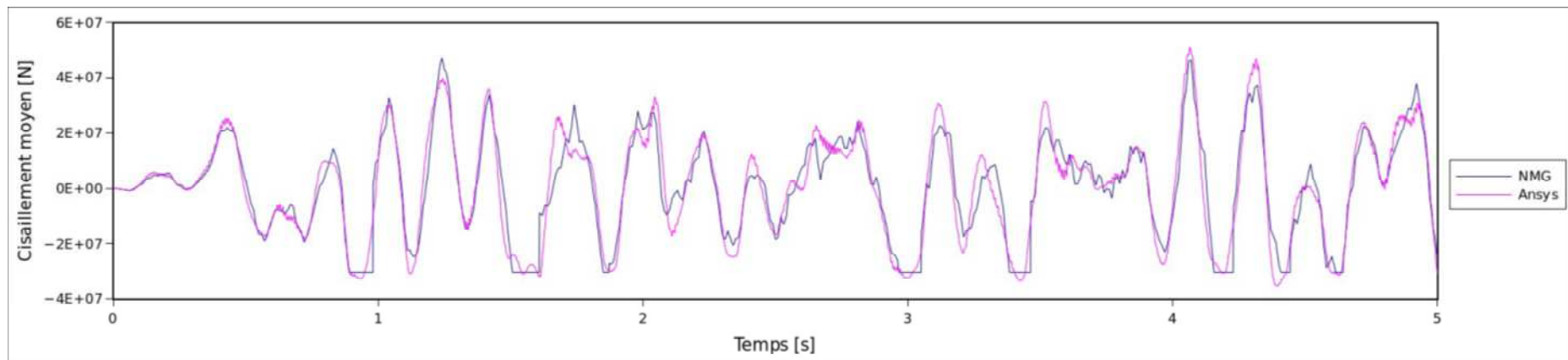
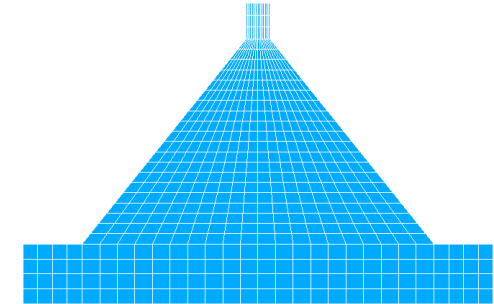
- **ANSYS model hypothesis**

- Rayleigh damping proportional to the stiffness matrix
- Pore-pressures taken into account in the a_{lim} value
- No fluid domain (only added masses) & infinitely rigid foundation

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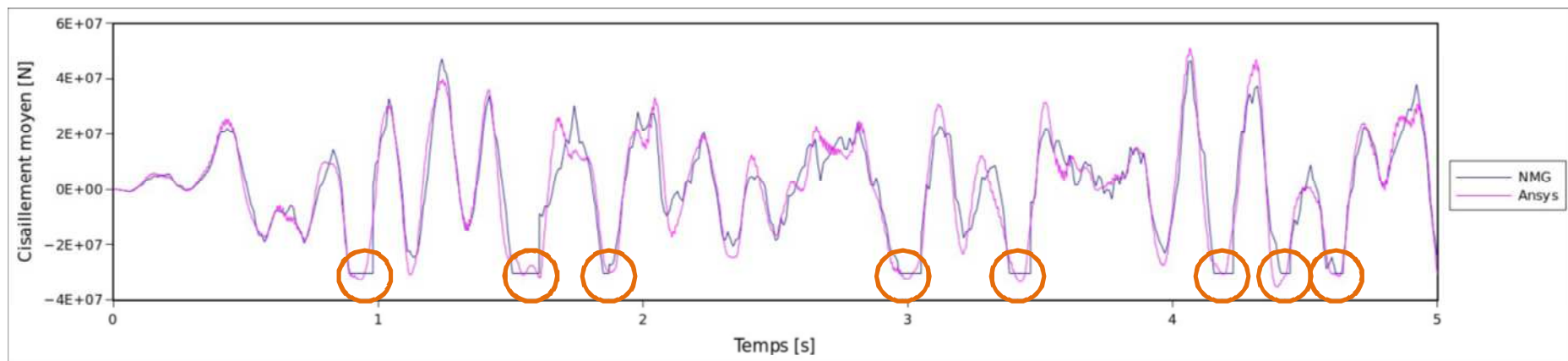
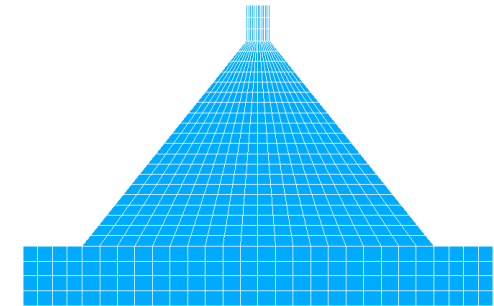
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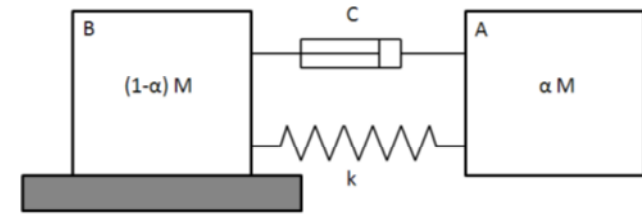


SLIDING !

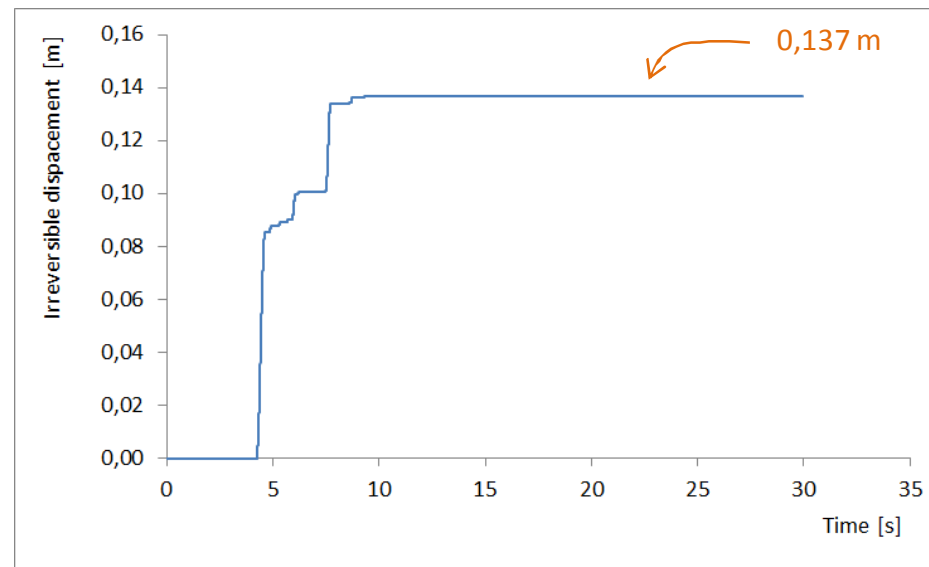
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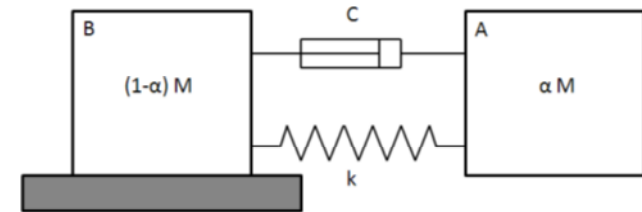
SLIDING CALCULATION



- The motion integration gives the final irreversible sliding
 - One or two degrees of freedom
 - Fundamental principle of the dynamics
 - The result *does not* depend on the total mass M !
- An example of sliding calculation



SLIDING CALCULATION



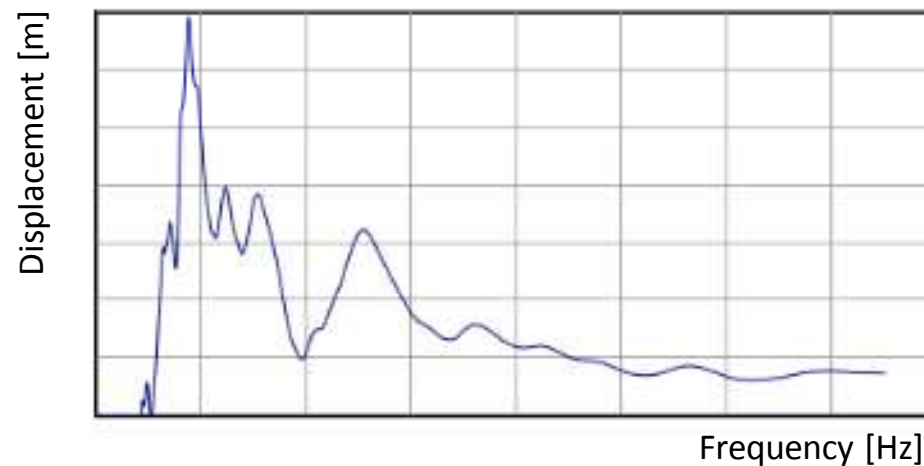
▪ Let's define the sliding spectra

- A sliding spectrum is drawn for a set of parameters :

- ❖ α
- ❖ ξ
- ❖ a_{lim}

- The sliding spectra give the final **displacement** of the mass B as a function of the **fundamental frequency** f

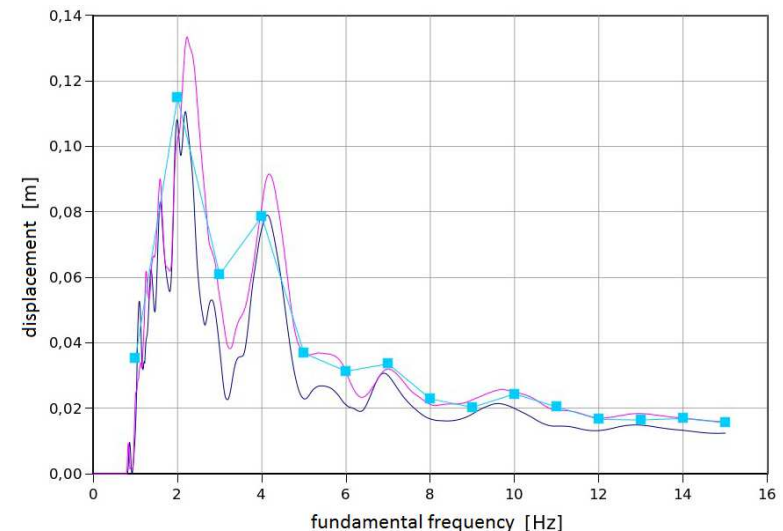
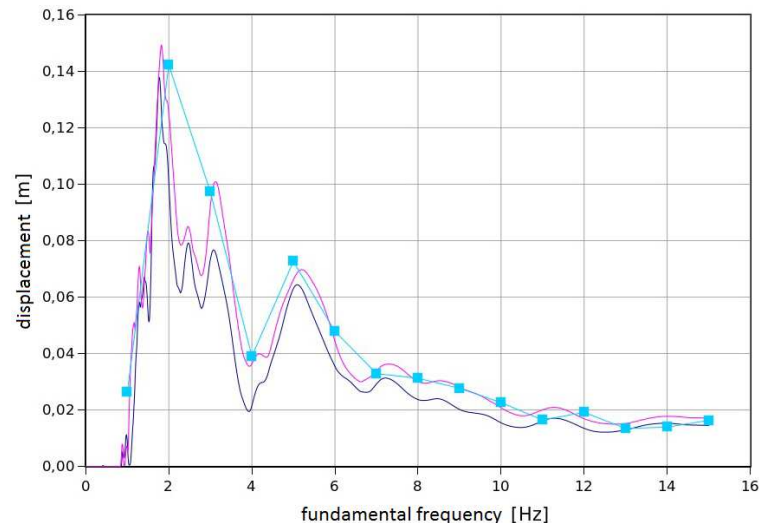
▪ Shape of a sliding spectrum



SLIDING SPECTRA COMPARISON

■ With two examples

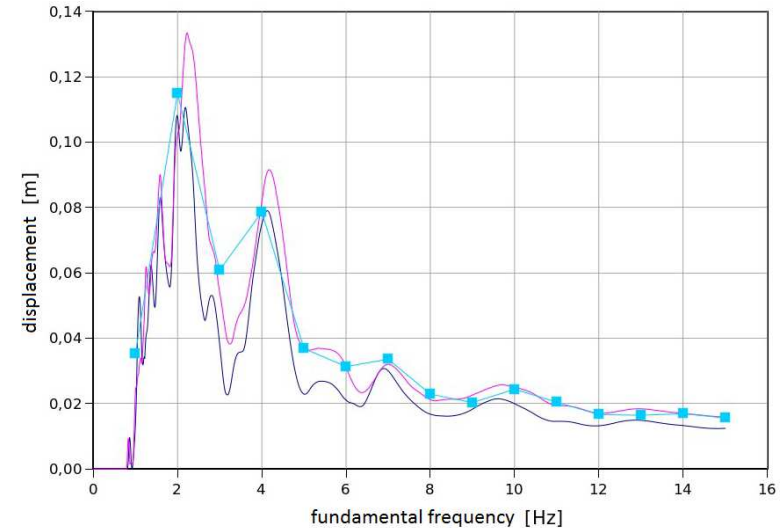
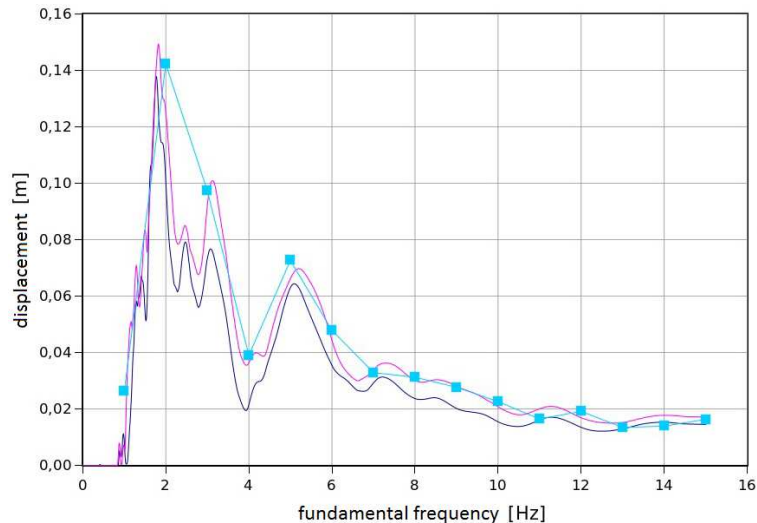
- Sliding calculated with Code_Aster[®] (JOINT_MECA_FROT)
- Sliding calculated with the simplified method



■ Code_Aster model hypothesis

- Rayleigh damping proportional to the stiffness matrix
- Pore-pressures taken into account in the a_{lim} value
- No fluid domain (only added masses) & infinitely rigid foundation

SLIDING SPECTRA PROS AND CONS



- **Sliding spectra :**
 - Are easy to define and to understand
 - Are easy to compute and to use
 - Are computed in less than 10 seconds with a personal computer !
- **But some phenomena are not taken into account, especially :**
 - Soil-structure interaction
 - Fluid-structure interaction
 - Cohesion

SLIDING SPECTRA APPLICATIONS

- The main advantage of this simplified method is the number of possible applications : **parametric & probabilistic studies**
- Amount of computation for a probabilistic study
 - For each random parameter defined by its probability distribution
~ 10^2 simulations
 - Let's suppose that 2 parameters are defined as random
~ 10^4 simulations
 - That-is-to say : **10 000 simulations** for :
 - ❖ each geometry
 - ❖ each foundation resistance hypothesis
 - ❖ each accelerogram
- Some examples are given in ref [2]

IMPROVING SIMPLIFIED MODELS

**WHEN AN ANALYTICAL SOLUTION OF A PHENOMENON EXISTS,
EVEN AN APPROXIMATED ONE,
A SIMPLIFIED MODEL CAN BE BUILT**

- **SOIL-STRUCTURE INTERACTION**
 - The Wolf & Deeks Cone (2010)

- **VERTICAL FLUID BEHAVIOR**
 - Vertical modes
 - Mean pressure on the dam

- **FLUID-STRUCTURE INTERACTION**

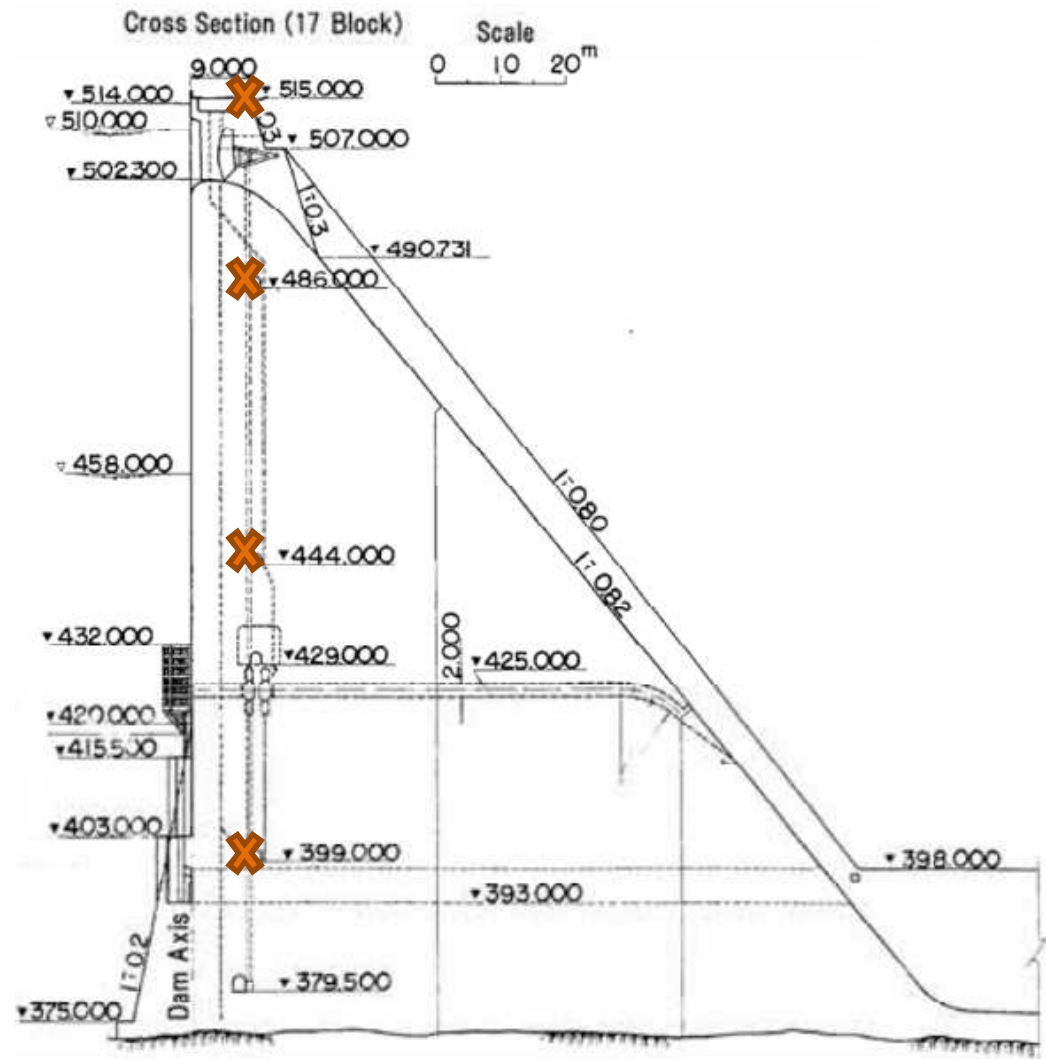
AN EXAMPLE OF REAL RECORDS

■ TAGOKURA DAM

- Concrete gravity dam
- Height: 145 m
- Crest length: 462 m

■ RECORDS (3 directions)

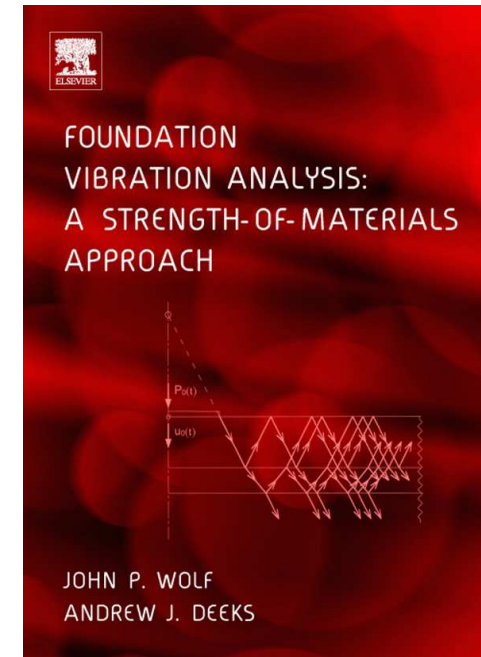
- El 399 (lower gallery)
- El 444
- El 486
- El 515 (crest)



SOIL-STRUCTURE INTERACTION

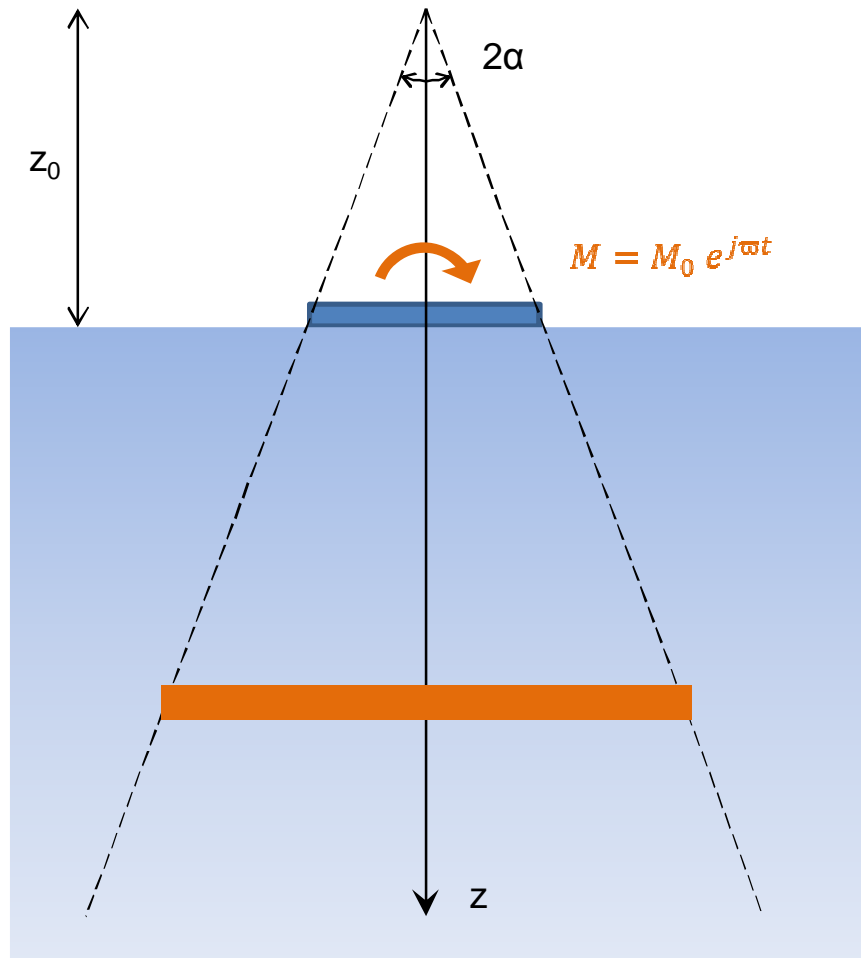
■ The Wolf & Deeks Cone (2004)

- The soil impedance is approximated with
 - ❖ springs
 - ❖ dampers
 - ❖ masses
 - ❖ etc.
- The soil is replaced by a cone-shaped beam of soil
- Analytical solutions exist for
 - ❖ the vertical impedance
 - ❖ the horizontal impedance
 - ❖ the rocking impedance
 - ❖ the rotation impedance
- Quite **accurate representation of the ISS**, a lot of comparisons are made



SOIL-STRUCTURE INTERACTION

Rocking impedance



Hypothesis

- The foundation is rigid
- The cone behaves as a Bernoulli beam
- The foundation is only rocking

Fundamental equations

- Equilibrium (FPD)

$$\frac{\partial M}{\partial z} + \rho I \omega^2 \theta = 0$$

- Material behavior

$$M = EI \frac{\partial \theta}{\partial z}$$

- Geometry

$$I = I_0 \left(\frac{z}{z_0} \right)^n$$

n = 3 for 2D models
n = 4 for 3D models

SOIL-STRUCTURE INTERACTION

- Soil behavior equation

$$\frac{\partial^2 \theta}{\partial z^2} + \frac{n}{z} \frac{\partial \theta}{\partial z} + \frac{\omega^2 \theta}{V_p^2}$$

- Solution for 2D models : $n = 3$ →



- Solution for 3D models : $n = 4$

$$\theta(z, \omega) = \left(\frac{1}{z^3} + j \frac{\omega}{V_p} \frac{1}{z^2} \right) e^{-j \frac{\omega}{V_p} z}$$



Relation between θ and $\partial^2 \theta / \partial z^2$



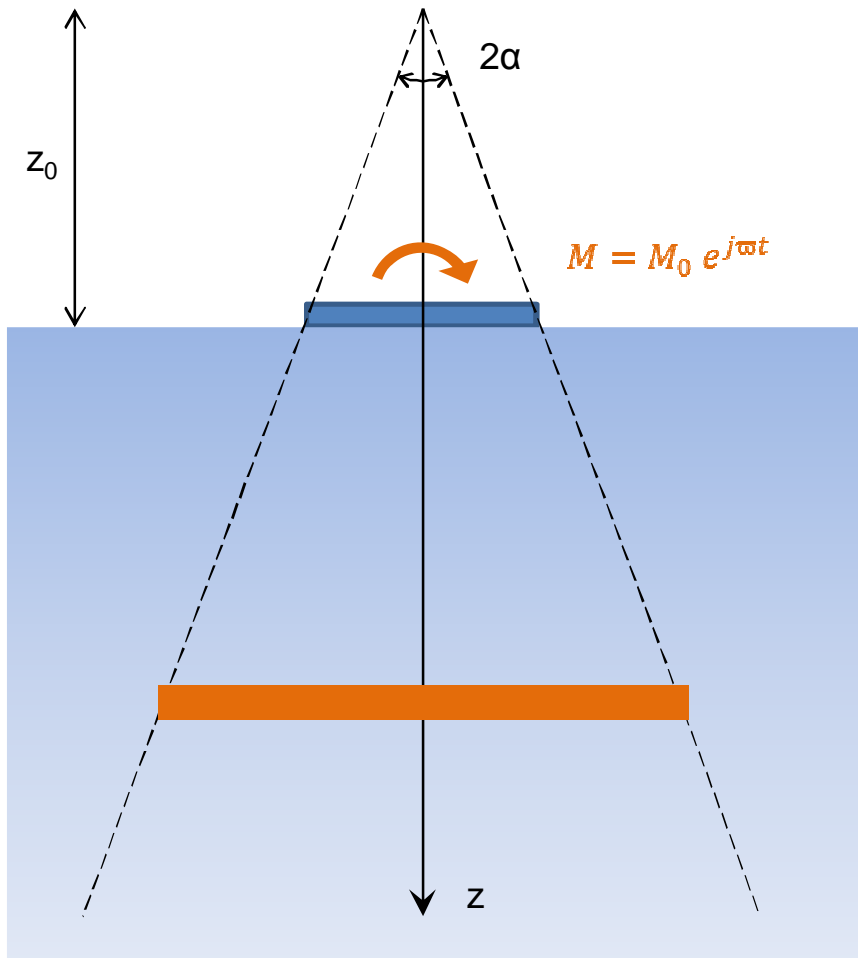
Calibration on the static solution to determines the equivalent soil system



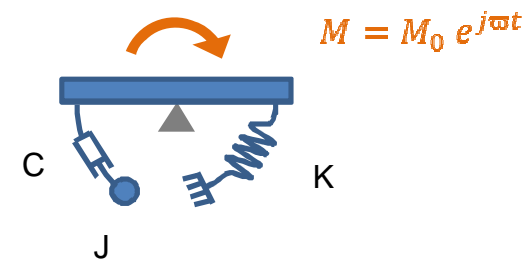
Analytical expression of impedance

SOIL-STRUCTURE INTERACTION

- Rocking impedance



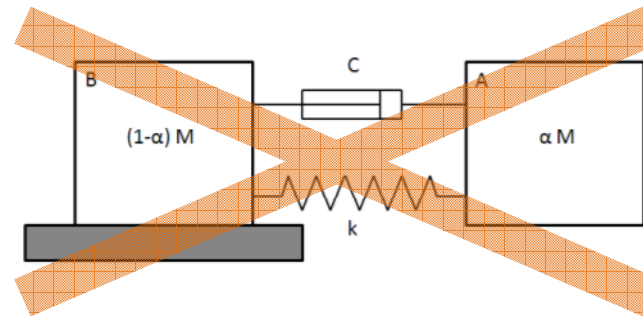
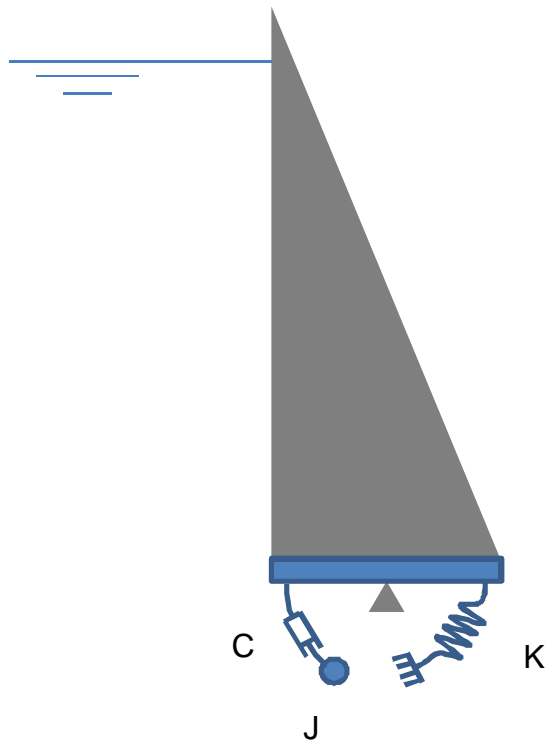
- Equivalent soil system



C, J, K are defined analytically,
and *does not* depend on ω

SOIL-STRUCTURE INTERACTION

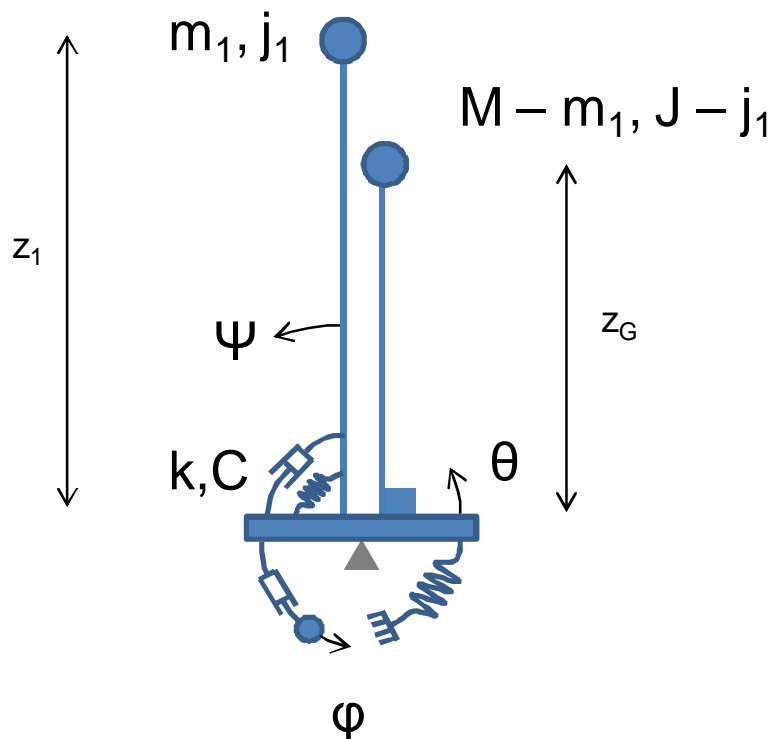
- How to simply represent the dam?



This simple model is no longer valid:
it should model the **total momentum** at the
foundation, not the **shear force**

SOIL-STRUCTURE INTERACTION

- How to simply represent the dam?



- Parameters

- M : total mass
- m_1 : first modal mass

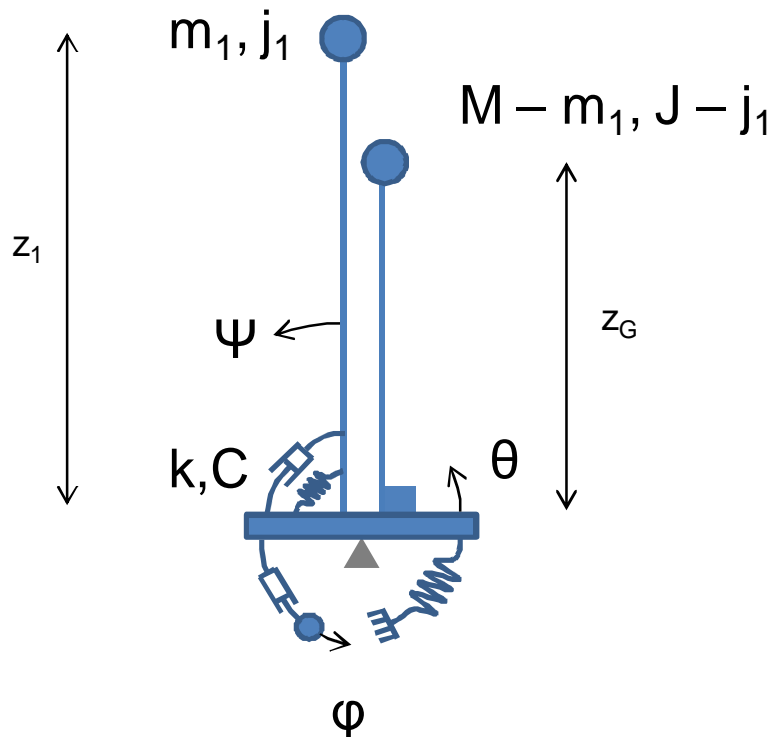
$$m_1 = \frac{(D_1 \underline{M} \Delta)^2}{D_1 \underline{M} D_1}$$

- J : total moment of inertia
- j_1 : first modal moment of inertia

$$j_1 = \frac{(D_1 \underline{M} B)^2}{D_1 \underline{M} D_1}$$

- k, C : first mode of the dam on a rigid foundation

SOIL-STRUCTURE INTERACTION



- Elevation z_1 and z_0

- $z_1 = (j_1 / m_1)^{0,5}$
- z_G = elevation of the centre of gravity

- The « demonstration » is similar to the one presented for the first model

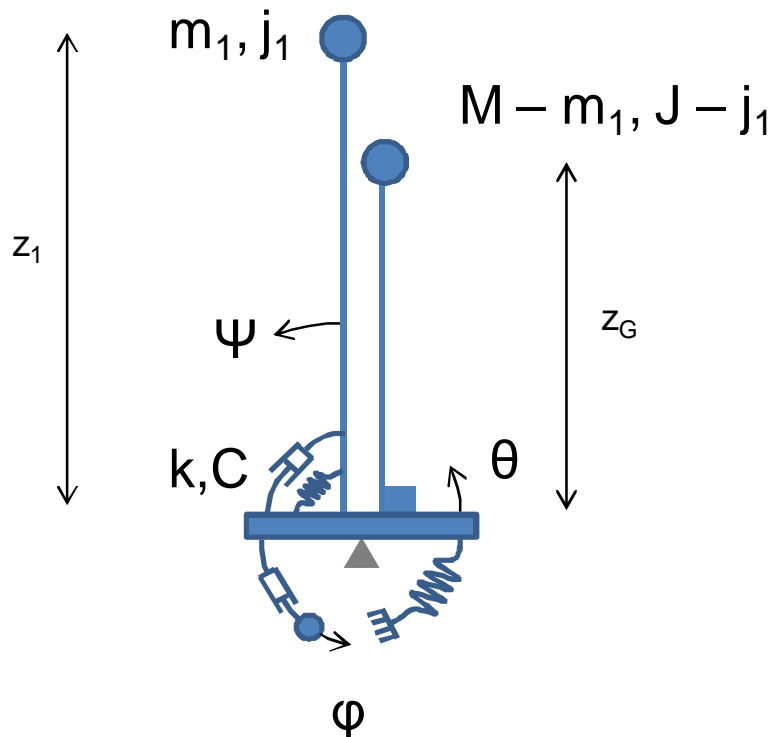
- Crest horiz. displacement

$$d_c = \theta H + \delta z_1 \psi$$

$$\delta = a_1 D_1(z = H)$$

SOIL-STRUCTURE INTERACTION

- What is the effect of the SSI?
 - Transfer function between the horiz. acceleration and the crest acc.



- Matrices of the simplified system

- $\underline{\underline{M}}, \underline{\underline{C}}, \underline{\underline{K}}$

- Motion equation

$$(-\omega^2 \underline{\underline{M}} + j\underline{\underline{C}}\omega + \underline{\underline{K}}).\underline{\underline{X}} = \underline{\underline{\Delta}}' a(\omega) e^{j\omega t}$$

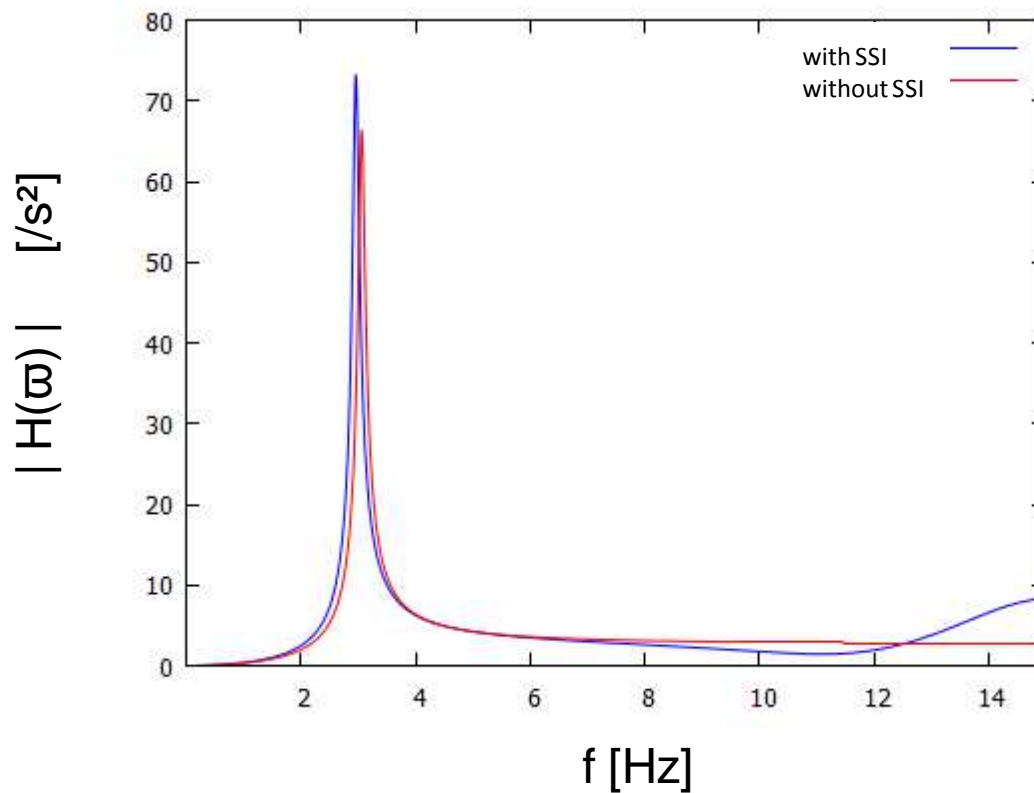
- Crest horiz. displacement

$$d_c = \theta H + \delta z_1 \psi = \underline{\underline{R}}.\underline{\underline{X}}$$

$$d_c = \underline{\underline{R}}.(-\omega^2 \underline{\underline{M}} + j\underline{\underline{C}}\omega + \underline{\underline{K}})^{-1} \underline{\underline{\Delta}}' a(\omega) e^{j\omega t}$$

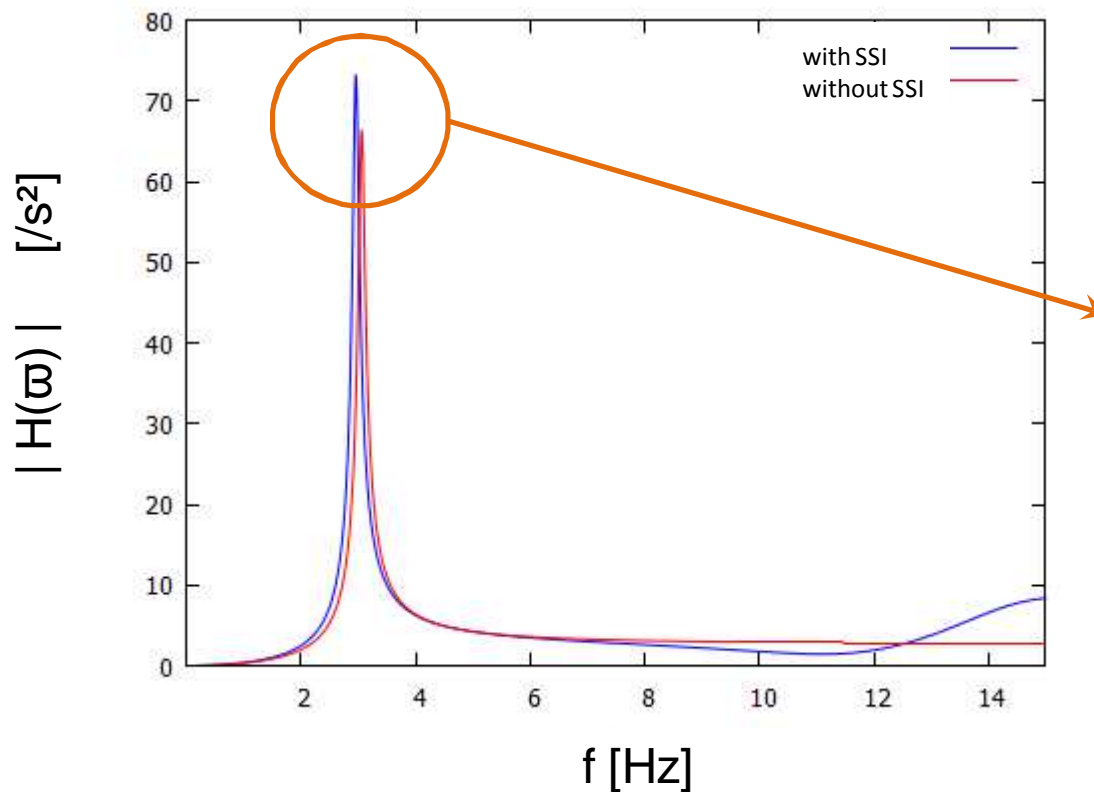
SOIL-STRUCTURE INTERACTION

- What is the effect of the SSI?
 - **Transfer function** between the horiz. acceleration and the crest acc.



SOIL-STRUCTURE INTERACTION

- What is the effect of the SSI?
 - Transfer function between the horiz. acceleration and the crest acc.



In this case (Tagokura):

- Almost no SSI damping
- Almost no effect on the fundamental frequency

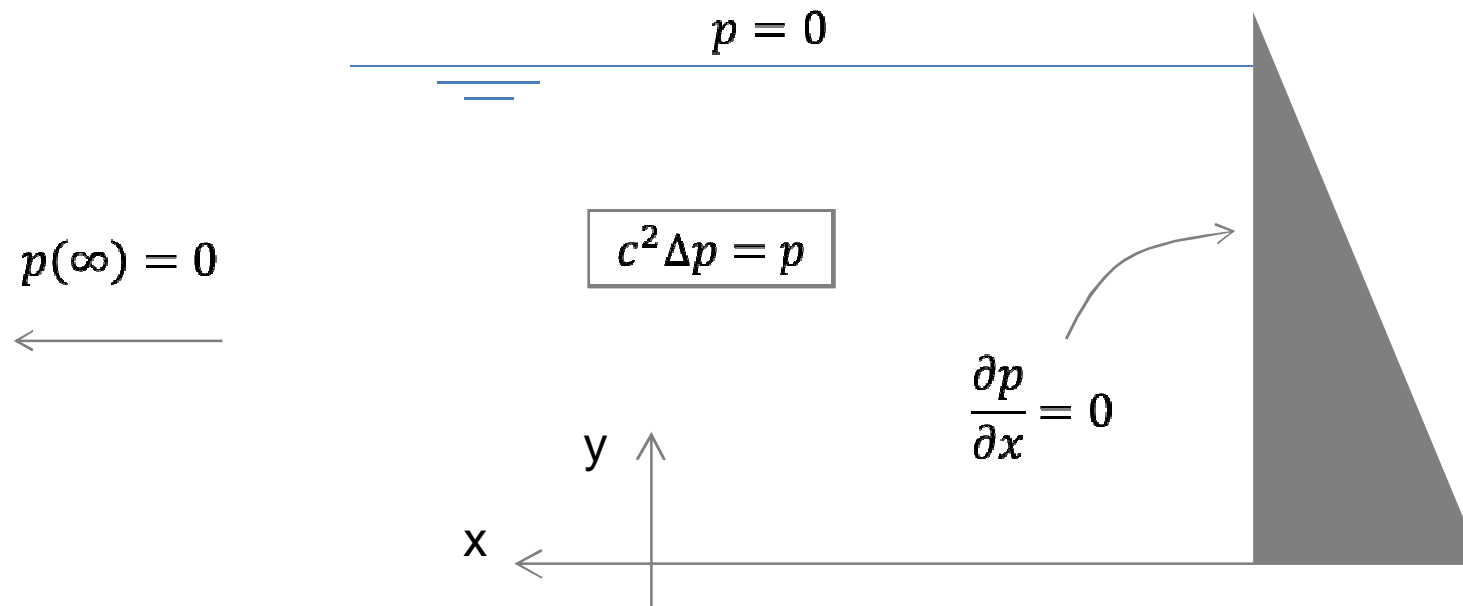
SOIL-STRUCTURE INTERACTION

- What is the effect of the SSI?
 - In the Tagokura case : almost no effect of the rocking impedance
 - The horizontal impedance may have more effect : *to be continued*

VERTICAL FLUID BEHAVIOR

- The vertical earthquake effect on a reservoir has been investigated by ref [4]
- Vertical acceleration generates a vertical response of the reservoir
- This response generates a pressure on the upstream face

VERTICAL FLUID BEHAVIOR



Bottom condition

- Total absorption = Sommerfeld
→

$$\frac{\partial p}{\partial y} + \frac{1}{c} \frac{\partial p}{\partial t} = -\rho a_y$$
- Total reflection = Rigid condition
→

$$\frac{\partial p}{\partial y} = -\rho a_y$$
- Realistic behavior
→

$$\frac{\partial p}{\partial y} + \frac{h}{c} \frac{\partial p}{\partial t} = -\rho a_y$$

VERTICAL FLUID BEHAVIOR

- **Pressure in the fluid**

- Under vertical acceleration, the pressure *does not* depend on x

$$P(y, t) = \frac{\cos \lambda H - \cot \lambda H \sin \lambda y}{\lambda \cot \lambda H - j \omega \frac{h}{C}} \rho a_y(\omega) e^{j \omega t} \quad \lambda = \frac{\omega}{C}$$

- **Eigenvalues** are given by $\cos \lambda H = 0$

$$f = \frac{1 \pi C}{4 H} ; \frac{3 \pi C}{4 H} ; \frac{5 \pi C}{4 H} ; \dots$$

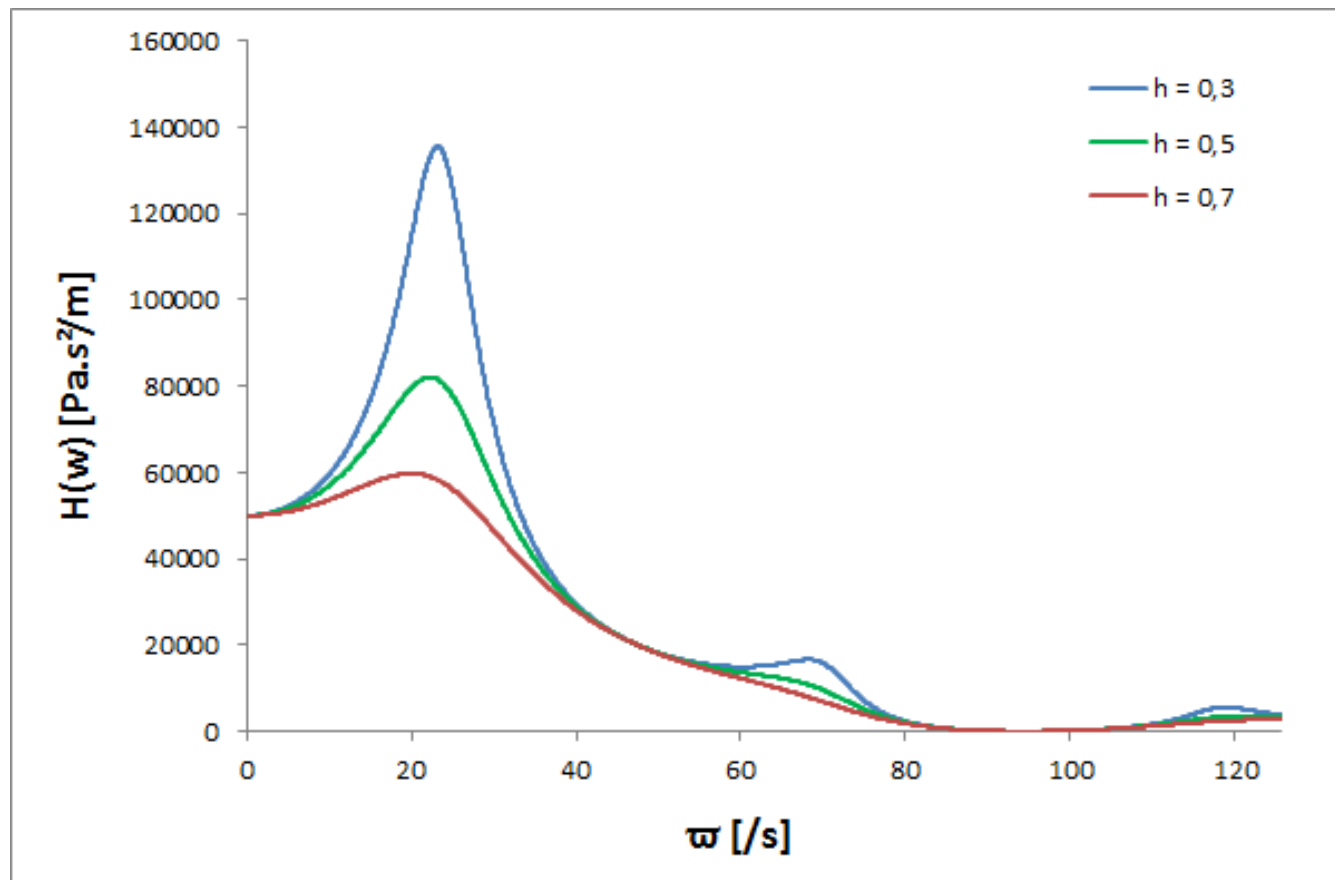
- The **mean pressure on the upstream face** is

$$\bar{P}(t) = \int P(y, t) dy$$

- The mean pressure is a force-sollicitation on the dam

VERTICAL FLUID BEHAVIOR

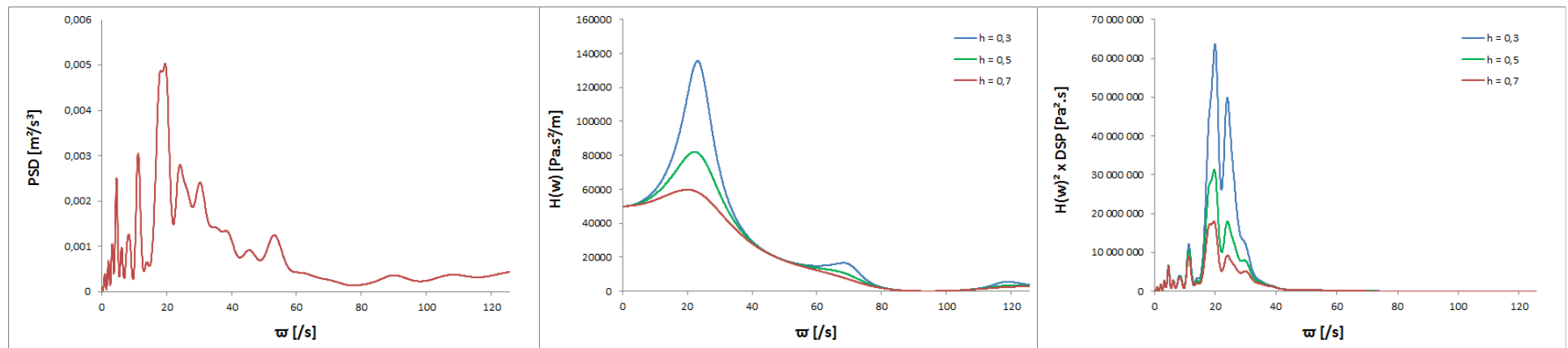
- Mean pressure v.s. vertical acceleration : transfer function
 - Influence of the parameter h



VERTICAL FLUID BEHAVIOR

- **Rough estimation of the mean pressure on the upstream face**

- Assuming that the vertical acceleration is a stochastic function, the value of the mean pressure on the upstream face can be estimated using the Power Spectral Density



$$E(\max(\bar{P})) = \text{peak} \times \int |H(\omega)|^2 PSD(\omega) d\omega = \begin{cases} 14\% & \text{of } \rho g H / 2 \text{ for } h = 0,3 \\ 10\% & \text{of } \rho g H / 2 \text{ for } h = 0,5 \\ 08\% & \text{of } \rho g H / 2 \text{ for } h = 0,7 \end{cases}$$

$\text{peak} \rightarrow \approx 3$

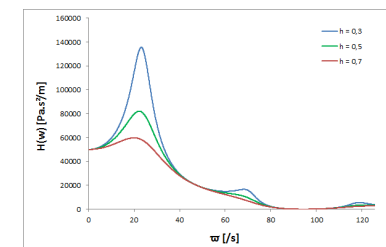
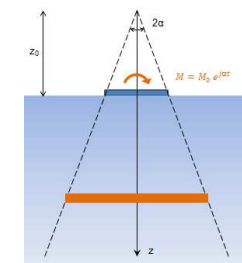
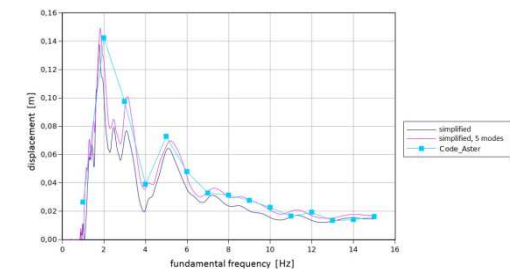
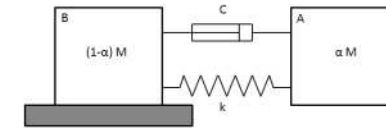
With a vertical PGA = 0,08 g

FLUID-STRUCTURE INTERACTION

- **First approximation : Westergaard**
 - Valid under strict conditions
- **For high dams**
 - General analytical solutions have been proposed, see ref [5] and [6]
 - So, simplified models could be built
 - To be continued...

CONCLUSIONS AND PERSPECTIVES

- We believe that simplified models can usefully be further developed
- Historical simplified dynamic models have been developed by others, for gravity or earthfill dams, and have proven being useful
- Some applications (parametric & probabilistic studies) need simplified models
- For gravity dams, a first 2D simplified model incorporating various aspects of dam dynamics has been developed and compared to more complex FEM models
- Several aspects still have to be incorporated (SSI, FSI, underpressures). It has not been implemented so far, but it seems possible
- The PN represents a unique opportunity to keep working on these methods



THANK YOU FOR
YOUR ATTENTION

